

$$\textcircled{1} \quad |\vec{R}| = \sqrt{A^2 + B^2 + 2AB \cos \theta}$$

$$\tan \phi = \frac{B \sin \theta}{A + B \cos \theta}$$

② Eqs of Motion

$$1^{\text{st}}: v = u + at$$

$$2^{\text{nd}}: s = ut + \frac{1}{2}at^2$$

$$3^{\text{rd}}: v^2 = u^2 + 2as$$

$$\textcircled{3} \quad S_n = u + \frac{a}{2}(2n-1)$$

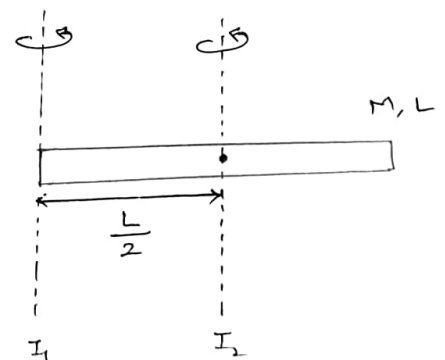
$$\textcircled{4} \quad v_{\text{instantaneous}} = \frac{dx}{dt}$$

$$\textcircled{5} \quad \boxed{I_2 = \frac{ML^2}{12}}$$

For  $I_1$ , we apply parallel axis theorem

$$\begin{aligned} \therefore I_1 &= I_2 + M \left(\frac{L}{2}\right)^2 \\ &= \frac{ML^2}{12} + \frac{ML^2 \times 3}{4 \times 3} \end{aligned}$$

$$\boxed{I_1 = \frac{ML^2}{3}}$$



$$\textcircled{6} \quad I = \frac{2}{5} MR^2$$

$$\textcircled{7} \quad I = mr^2$$

$$\textcircled{8} \quad \boxed{I_3 = \frac{ML^2}{6}}$$

now,  $I_1$  and  $I_2$  are symmetrically "equivalent".

$$\therefore \text{Let } I_1 = I_2 = I'$$

now, we apply perpendicular axis theorem,

$$I_3 = I_1 + I_2$$

$$I_3 = I' + I'$$

$$\therefore I' = \boxed{\frac{ML^2}{12} = \cancel{I_3} \quad I_1 = I_2}$$

now, for  $I_4$  we can apply parallel axis theorem

$$\begin{aligned} I_4 &= I_1 + M\left(\frac{L}{2}\right)^2 \\ &= \frac{ML^2}{12} + \frac{ML^2 \times 3}{4 \times 3} \end{aligned}$$

$$\boxed{I_4 = \frac{ML^2}{3}}$$

$$\textcircled{9} \quad \begin{array}{ll} \text{a) } t = \sqrt{\frac{2h}{g}} & \text{b) } v = \sqrt{2gh} \end{array}$$

$$(10) \quad a = v \left( \frac{dv}{dx} \right)$$

(11)

$$a) \quad y_{\text{com}} = \frac{h}{4} \quad (\text{solid})$$

$$b) \quad y_{\text{com}} = \frac{h}{3} \quad (\text{hollow})$$

$$b) \quad \text{Ring,} \quad y_{\text{com}} = \frac{2R}{\pi}$$

$$\text{Disc,} \quad y_{\text{com}} = \frac{4R}{3\pi}$$

$$c) \quad \text{Hemispherical shell,} \quad y_{\text{com}} = \frac{R}{2}$$

$$\text{solid Hemisphere,} \quad y_{\text{com}} = \frac{3R}{8}$$

(12)

$$a) \quad I_p = 0 \quad (r < R)$$

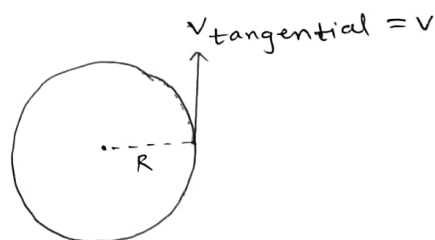
$$I_p = \frac{GM}{r^2} \quad (r > R)$$

(13)

$$a) \quad \vec{v} = \vec{\omega} \times \vec{r}$$

$$b) \quad a_c = \frac{v^2}{r}$$

$$c) \quad a_t = \frac{dv}{dt} \rightarrow v_{\text{tangential}}$$



$$d) \quad a = \sqrt{a_c^2 + a_t^2}$$

(14) Eqn of Trajectory:

$$y = x \tan \theta - \frac{1}{2} \cdot \frac{g x^2}{u^2 \cos^2 \theta}$$

(15)  $W = \vec{F} \cdot \vec{s}$

$$= \int \vec{F} \cdot d\vec{s} \quad (\text{Integral form})$$

(16) b) Solid Sphere

$$I_p = \frac{GM r}{R^3} \quad (r < R)$$

$$I_p = \frac{GM}{r^2} \quad (r > R)$$

(17)  $J = \int F dt$

(18) Impulse - momentum Theorem :  $J = \Delta p$

(19)  $v_{esc} = \sqrt{2gR}$

(20) 
$$I_1 = \frac{MR^2}{2}$$

Now  $I_2$  and  $I_3$  are equivalent due to symmetry  
↓

$$I_1 = I_2 + I_3 \quad (\because \text{Let } I_2 = I_3 = I_d)$$

$$I_1 = I_d + I_d$$

$$\therefore I_d = \frac{MR^2}{4} = I_2 = I_3$$

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$$e = \frac{V_{sep}}{V_{app}} = \frac{v_1 + v_2}{u_1 - u_2} \quad (\text{for the given case})$$

22

$$B = \frac{-P}{\left(\frac{\Delta V}{V}\right)}$$

23

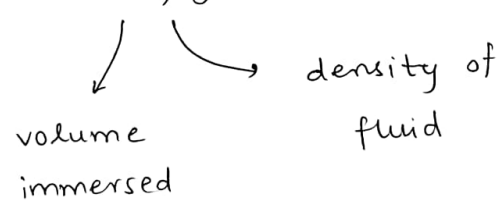
$$a) \quad g' = \frac{g}{\left(1 + \frac{h}{R}\right)^2} \approx g \left(1 - \frac{2h}{R}\right)$$



$$b) \quad g' = g \left(1 - \frac{d}{R}\right)$$

24 Eqn of continuity :  $Av_1 = av_2$

25  $F_B = V \rho g$



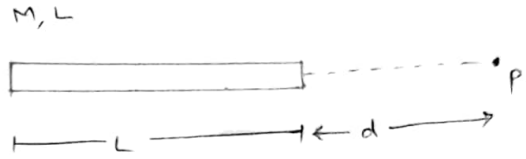
26 Areal velocity  $\Rightarrow \boxed{\frac{dA}{dt} = \frac{L}{2m}}$

$L \Rightarrow$  angular momentum

$m \Rightarrow$  mass

$$(27) \quad I_1 = \frac{2}{3} MR^2$$

$$(28) \quad I_p = \frac{GM}{(L+d)d} \quad (\text{rod})$$



$$I_p = \frac{GM}{R^2} \cdot \left( \frac{\sin \theta}{\theta} \right) \quad (\text{for circular arc})$$

$$(29) \quad |\vec{\tau}| = r F \sin \theta$$

$$\vec{\tau} = \vec{r} \times \vec{F} \quad (\text{vector form})$$

$$(30) \quad \boxed{T.E = -K.E = \frac{P.E}{2}}$$

$$(31) \quad \text{i) } \omega = \omega_0 + \alpha t$$

$$\text{ii) } \theta = \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\text{iii) } \omega^2 = \omega_0^2 + 2\alpha\theta$$

$$(32) \quad P_A = P_0 + \rho g h$$

$$(33) \quad P_1 + \rho g h_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g h_2 + \frac{1}{2} \rho v_2^2$$

↑  
Bernoulli's Theorem

34

i)  $V_p = \ominus \frac{GM}{r}$  ( $r > R$ )

ii)  $V_p = \ominus \frac{GM}{2R^3} (3R^2 - r^2)$  ( $r < R$ )

ii) on the axis of ring

$$V_p = \ominus \frac{GM}{\sqrt{R^2 + x^2}}$$

35

$\alpha : \beta : \gamma = 1 : 2 : 3$  .

36

work done by all forces	= $\Delta k.E$	(original)
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}	$\Delta k + \Delta U = W_{nc} + W_{other} \text{ (except c)}$
	$\downarrow$ non-conservative $\downarrow$ conservative

→ Modified form of Work - Energy Theorem  
(Optional)

37

$\tan \theta = \frac{a}{g}$

38

$\frac{dT}{dt} = k [T_{avg} - T_0]$

$\downarrow$  rate of cooling                       $\downarrow$  surrounding Temperature.

$$(39) \quad \gamma = \frac{\text{stress}}{\text{strain}}$$

$$(40) \quad \Delta Q = \Delta U + W$$

$$(41) \quad C_p - C_v = R$$

$$(42) \quad P = \frac{1}{3} \rho v_{rms}^2$$

Type	f	$C_p$	$C_v$
mono	3	$\frac{5R}{2}$	$\frac{3R}{2}$
di	5	$\frac{7R}{2}$	$\frac{5R}{2}$
Tri (linear)	5	$\frac{7R}{2}$	$\frac{5R}{2}$
Tri (non-linear)	6	$4R$	$3R$

$$(44) \quad v_{rms} > v_{avg} > v_{mp}$$

$$(45) \quad T = 2\pi \sqrt{\frac{I}{mgd}}$$

(46) Stefan's Law

$$P = e\sigma AT^4$$

$$(47) \quad F = -\frac{dU}{dx}$$

(48) For string,

$$v_{min}(\text{bottom}) = \sqrt{5gR}$$

For rod,

$$v_{min}(\text{bottom}) = \sqrt{4gR}$$

$$(49) \quad F_t = -u \left( \frac{dm}{dt} \right)$$

(50) Wadiabatic =? (w)

$$W = \frac{1}{1-\gamma} (P_2 V_2 - P_1 V_1)$$

$$(51) \quad v_p = \ominus \frac{GM}{R} \quad (r < R)$$

$$v_p = \ominus \frac{GM}{r} \quad (r > R)$$



52

$$\frac{dQ}{dt} = kA \left( \frac{dT}{dx} \right)$$

53

$$v = \pm w \sqrt{A^2 - x^2}$$

54

$$W_{\text{isothermal}} = nRT \ln \left( \frac{V_2}{V_1} \right)$$

55

$$v_T = \frac{2}{9} \cdot \frac{r^2 g (\rho - \rho_L)}{\eta}$$

56

$$\mu = \frac{\text{Lateral strain}}{\text{Longitudinal strain}} = \ominus \frac{(\Delta r/r)}{(\Delta l/l)}$$

57

$$\tau = I \alpha$$

58

$$\vec{L} = m (\vec{r} \times \vec{v})$$

[ for point mass ]

$$\vec{L} = I \vec{\omega}$$

( bodies )

59

(i)  $\rightarrow$  isobaric

(ii)  $\rightarrow$  isothermal

(iii)  $\rightarrow$  adiabatic

(iv)  $\rightarrow$  isochoric

$$(60) \quad T = 2\pi \sqrt{\frac{m}{k_1 + k_2}}$$

$$(61) \quad U = \frac{1}{2} k A^2$$

$$(62) \quad T = 2\pi \sqrt{\frac{I}{C}} \quad C \rightarrow \text{Torsional constant}$$

(63) Weins Displacement Law

$$\lambda \propto \frac{1}{T} \Rightarrow \lambda T = b = \text{constant}$$

(64) Ideal gas equation

$$PV = nRT$$

$$(65) \quad v_{\text{rms}} = \sqrt{\frac{3RT}{M}}$$

$$v_{\text{mp}} = \sqrt{\frac{2RT}{M}}$$

$$v_{\text{avg}} = \sqrt{\frac{8}{\pi} \frac{RT}{M}}$$

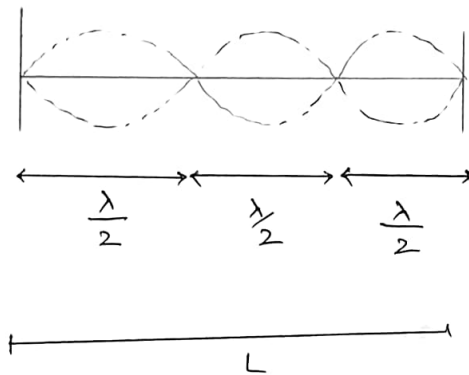
$$(66) \quad \eta = 1 - \frac{T_2}{T_1}$$

$$(67) \quad W = 0$$

$$(68) \quad v_{\text{wave}} = \frac{\omega}{k}$$

$$(69) \quad C = \frac{\Delta Q}{n \Delta T}$$

(70) string is fixed at both ends



$$\therefore L = 3 \frac{\lambda}{2} \Rightarrow \therefore \lambda = \frac{2L}{3}$$

We know,

$$v = f \lambda$$

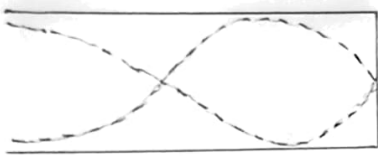
$$\therefore f = \frac{v}{\left(\frac{2L}{3}\right)} = \frac{3v}{2L}$$

$$\therefore \boxed{f = \frac{3v}{2L}} \quad (\text{freq})$$

$$(71) \quad \Delta\phi = \left(\frac{2\pi}{\lambda}\right) \cdot \Delta x \quad (\text{with } x)$$

$$\Delta\phi = \left(\frac{2\pi}{T}\right) \cdot \Delta t \quad (\text{with } t)$$

(72)



$$(73) \quad a = -\omega^2 x$$

$$(74) \quad U = n C_v \Delta T = \frac{f}{2} n R \Delta T$$

$$(75) \quad k = \frac{R}{N_A}$$

$$(76) \quad E = \frac{1}{2} k T$$

$$(77) \quad T = 2\pi \sqrt{\frac{l}{g}}$$

$$(78) \quad k = \frac{2\pi}{\lambda}$$

$$(79) \quad v_{\text{apparent}} = \left(\frac{v \pm v_o}{v \pm v_s}\right) v_{\text{actual}}$$

80  $I = 2\pi^2 f^2 A^2 \rho v$

81 a) Units of  $G$  :  $\text{Nm}^2\text{kg}^{-2}$

b) Unit of  $R$  :  $\text{JK}^{-1}\text{mol}^{-1}$

c) Unit of  $b$  :  $\text{m}^{-1}\text{k}$

d) Intensity unit :  $\text{W}/\text{m}^2$